

# Euclidean Geometry

Navigation

**Prerequisites:** None (foundational)

**Enables:** Trigonometry, Coordinate Geometry, Linear Algebra, Calculus

## Introduction

Euclidean geometry forms the spatial reasoning foundation essential for machine learning. From understanding projections in high-dimensional spaces to grasping optimization landscapes, these concepts are fundamental prerequisites.

### ! Why This Matters for Machine Learning

- **Vector Spaces:** Geometric objects with distance and angles
- **Optimization:** Gradient descent as geometric motion
- **Dimensionality Reduction:** Projections preserve geometric structure
- **Kernel Methods:** Distance-based similarity in feature space
- **Neural Networks:** Each layer performs geometric transformation

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## Axioms and Postulates

*“The laws of nature are but the mathematical thoughts of God.”* — Euclid

## Motivation & Context

### Historical Setting

In 3rd century BCE Alexandria, Euclid faced a challenge: how to organize all known geometry into a logical system? Rather than present thousands of disconnected facts, he identified a minimal set of **self-evident truths** from which everything else could be derived.

This revolutionary approach: - Established the axiomatic method still used in mathematics - Influenced formal logic and computer science - Demonstrated that complex knowledge can be built from simple foundations

### The Problem

Without axioms, we face **infinite regress**: - To prove theorem A, we need theorem B - To prove theorem B, we need theorem C - To prove theorem C, we need theorem D... - *Where does it end?*

Euclid's solution: Start with statements so obvious they need no proof.

## Modern Relevance

**In ML/CS:** - Programming languages have axioms (basic operations) - Formal verification systems use axiomatic foundations - Type theory builds on logical axioms - Probabilistic reasoning starts with probability axioms

**Key Insight:** Complex systems require foundational assumptions. The art is choosing the **minimal sufficient set**.

## Intuitive Picture

Think of axioms as the “rules of the game” for geometry:

**Point** → GPS coordinate (location, no size)

**Line** → Stretched string (shortest path)

**Plane** → Infinite tabletop (flat surface)

**Distance** → Measuring tape result

**Mental Model:** You have an infinite blank canvas and two tools: 1. **Unmarked straightedge** (draw lines)  
2. **Compass** (draw circles)

The axioms tell you: - What operations are allowed - What properties are guaranteed - What you can assume without proof

### Visualization Exercise

Close your eyes. Imagine two dots floating in space. Now imagine the shortest path between them. That path is unique—this is Postulate 1’s intuitive content.

## Precise Definitions

### Undefined Terms

Three concepts are **primitive** (undefined, but understood intuitively):

**Point:** An object with no dimensions (position only)

**Line:** A one-dimensional object extending infinitely in both directions

**Plane:** A two-dimensional flat surface extending infinitely

**Why undefined?** To avoid circular definitions. These are our starting vocabulary.

### Euclid’s Five Postulates

**Postulate 1** (Uniqueness of Line).

*Given any two distinct points  $P$  and  $Q$ , there exists exactly one line  $\ell$  passing through both.*

**Postulate 2** (Line Extension).

*Any line segment can be extended indefinitely in both directions to form a line.*

**Postulate 3** (Circle Construction).

*Given any point  $C$  (center) and any positive distance  $r$  (radius), there exists a circle with center  $C$  and radius  $r$ .*

**Postulate 4** (Right Angle Congruence).

*All right angles are congruent to one another.*

**Postulate 5** (Parallel Postulate).

*Given a line  $\ell$  and a point  $P$  not on  $\ell$ , there exists exactly one line through  $P$  parallel to  $\ell$ .*

## Common Notions (Axioms of Equality)

**CN1** (Transitivity). If  $a = b$  and  $b = c$ , then  $a = c$ .

**CN2** (Addition). If  $a = b$  and  $c = d$ , then  $a + c = b + d$ .

**CN3** (Subtraction). If  $a = b$  and  $c = d$ , then  $a - c = b - d$ .

**CN4** (Coincidence). Things that coincide are equal.

**CN5** (Whole vs Part). The whole is greater than any proper part.

## Why These Definitions

### Why These Specific Five Postulates?

**Postulates 1-4:** Relatively “obvious” - Can verify locally with physical tools - Match immediate intuition - Universally accepted

**Postulate 5:** Controversial! - Cannot verify by direct observation (requires infinite extension) - More complex statement - Led to 2000 years of attempted proofs

### Why Is Postulate 5 Special?

It's the only postulate that: 1. **Requires infinity:** Must extend lines infinitely to verify 2. **Determines curvature:** Characterizes flat (Euclidean) space 3. **Is independent:** Cannot be derived from Postulates 1-4

**Historical Impact:** Attempts to prove Postulate 5 from 1-4 ultimately led to: - Hyperbolic geometry (Lobachevsky, Bolyai) - Elliptic geometry (Riemann) - General relativity (Einstein)

### Why Axioms of Equality?

These establish **logical consistency:** - Enable substitution in proofs - Allow algebraic manipulation - Provide ordering relations

Without them, we couldn't reason about relationships between measurements.

## Key Properties

From these axioms, immediate consequences follow:

**Property 1** (Uniqueness). Given specific conditions, geometric objects are uniquely determined: - Two points  $\rightarrow$  one line - Center + radius  $\rightarrow$  one circle - Line + external point  $\rightarrow$  one parallel

**Property 2** (Existence). Geometric objects can always be constructed: - Lines can be drawn and extended - Circles always exist for any radius - Intersections occur (when not parallel)

**Property 3** (Consistency). No contradictions arise: - Equality is transitive and symmetric - Measurements can be compared - Whole  $>$  Part establishes order

## Main Theorems

These axioms enable us to prove *everything else*:

**Theorem 1.1** (Vertical Angles).

*When two lines intersect, vertical angles are congruent.*

**Theorem 1.2** (Triangle Angle Sum).

*The sum of interior angles in any triangle equals  $180^\circ$ .*

**Theorem 1.3** (SSS Congruence).

*Triangles with three pairs of congruent sides are congruent.*

**Theorem 1.4** (Pythagorean Theorem).

*In a right triangle:  $a^2 + b^2 = c^2$ .*

**Theorem 1.5** (Parallel Line Properties).

*When a transversal crosses parallel lines, corresponding angles are congruent.*

*All of these follow logically from the five postulates!*

## Computational Methods

### How to Use Axioms in Proofs

#### Standard Proof Structure:

Given: [What we know]

Prove: [What we want to show]

Proof:

1. [Statement]            [Reason: Given/Axiom/Previous theorem]
2. [Statement]            [Reason: ...]
- ...
- n. [Conclusion]          [Reason: ...]

**Example:** Prove base angles of isosceles triangle are equal.

Given: ABC with AB = AC

Prove: B = C

Proof:

1. Draw angle bisector AD from A to BC            [Construction]
2. BAD = CAD                                            [Definition of angle bisector]
3. AB = AC                                                [Given]
4. AD = AD                                                [Reflexive property]
5. ABD    ACD                                            [SAS congruence]
6. B = C                                                    [CPCTC]

### Verification Algorithm

To check if a proof is valid:

```
def verify_proof(proof_steps):
    """
    Verify each step cites proper justification.

    Returns: True if valid, False otherwise
    """
    known_facts = set(['given_facts', 'axioms', 'postulates'])

    for step in proof_steps:
        reason = step.reason
        if reason in ['Given', 'Axiom', 'Postulate']:
            known_facts.add(step.statement)
        elif reason in known_facts:
            known_facts.add(step.statement)
        else:
            return False # Invalid step

    return proof_steps[-1].statement == 'desired_conclusion'
```

## Examples Progression

### Example 1: Simplest Application

**Given:** Points  $A$  and  $B$

**Question:** How many lines pass through both?

**Solution:** By Postulate 1, exactly **one** line passes through any two distinct points.

**Verification:** Try to draw two different lines through both points—impossible!

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### Example 2: Standard Application

**Given:** Line  $\ell : y = 2x + 1$  and point  $P(3, 4)$  not on  $\ell$

**Question:** How many lines through  $P$  parallel to  $\ell$ ?

**Solution:**

By Postulate 5 (Parallel Postulate), exactly **one** line through  $P$  is parallel to  $\ell$ .

**Finding it:** Parallel lines have equal slopes.

Slope of  $\ell = 2$ , so parallel line:  $y - 4 = 2(x - 3)$ , i.e.,  $y = 2x - 2$ .

**Verification:**

- Passes through  $P$ :  $4 = 2(3) - 2 = 4$  - Same slope as  $\ell$ : Both have  $m = 2$  - Therefore parallel

---

### Example 3: Edge Case

**Given:** Point  $P$  on line  $\ell$

**Question:** How many lines through  $P$  parallel to  $\ell$ ?

**Answer: Zero!**

**Why:** The parallel postulate requires  $P$  **not** be on  $\ell$ . A line cannot be parallel to itself—by definition, parallel lines don't intersect.

**Common Error:** Thinking “a line is parallel to itself” (incorrect definition).

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### Example 4: Non-Example (Different Geometry)

**Context:** Geometry on a sphere's surface

**Setup:** Great circles (like equators) act as “lines”

**Observation:** Through a point  $P$  not on great circle  $\ell$ : - **Zero** parallel lines exist! - All great circles eventually intersect

**Conclusion:** This is **spherical (elliptic) geometry**, not Euclidean. Postulate 5 fails on spheres.

**Significance:** Shows Postulate 5 is truly necessary for Euclidean geometry.

## Common Pitfalls

### Mistakes to Avoid

#### Pitfall 1: Assuming What Needs Proof

*Wrong:* “The angles are equal because the figure looks symmetric”

*Right:* “By SAS congruence (using axioms), we prove angles are equal”

#### Pitfall 2: Visual “Proof”

*Wrong:* “The lines look parallel in my drawing”

*Right:* “The lines have equal slopes, hence by definition are parallel”

#### Pitfall 3: Applying Axioms Out of Scope

*Wrong:* Using Euclidean axioms on a sphere

*Right:* Recognize different geometries have different axiom sets

#### Pitfall 4: Circular Reasoning

*Wrong:* “Sides equal because angles equal, angles equal because sides equal”

*Right:* Establish one property from axioms, derive the other

#### Pitfall 5: Confusing Axioms with Theorems

*Wrong:* Trying to “prove” an axiom

*Right:* Axioms are accepted without proof; theorems are proved from axioms

## Connections

### Prerequisites

**Domain 0: Foundations - Logic & Proof:** Understanding of logical inference ( $\Rightarrow$ ,  $\Leftrightarrow$ ,  $\forall$ ,  $\exists$ ) - **Set Theory:** Points as elements, lines as sets of points

**Cognitive Prerequisites:** - Spatial reasoning ability - Abstract thinking - Comfort with logical arguments

### This Concept Enables

**Within Domain 2 (Geometry):** - All subsequent geometric theorems - Coordinate geometry (not yet covered) - Trigonometry (not yet covered)

**Other Domains:** - **Domain 5 (Linear Algebra):** Vector spaces as geometric objects - **Domain 7 (Real Analysis):** Metric spaces generalize distance - **Domain 9 (Optimization):** Geometric interpretation of convexity

### Related Concepts

**Non-Euclidean Geometries:** - **Hyperbolic:** Multiple parallels through external point (Postulate 5 altered) - **Elliptic:** No parallels (e.g., sphere surface) - **Taxicab:** Different distance metric

**Formal Systems:** - **Hilbert’s Axioms:** Modern rigorous reformulation - **Birkhoff’s Axioms:** Alternative minimal set - **Tarski’s Axioms:** First-order logic formulation

**ML Connections:** - Feature spaces as geometric objects - Metric learning modifies “distance” axioms - Graph neural networks on non-Euclidean domains

### Lean Formalization

```
-- Axiom 1: Two points determine a unique line
axiom point_line_incidence (P Q : Point) (h : P Q) :
  ! : Line, P Q

-- Axiom 5: Parallel postulate
axiom parallel_postulate ( : Line) (P : Point) (h : P ) :
```

```

! m : Line, P m parallel m

-- Theorem: Vertical angles are equal
theorem vertical_angles_equal ( : Angle)
  (h : vertical ) : = := by
  sorry -- Proof would follow from axioms

```

## Distance and Angle Measurement

### Motivation & Context

#### Why Precise Measurement Matters

**Ancient Applications:** - **Egypt (3000 BCE):** Re-surveying land after Nile floods - **Greece (500 BCE):** Navigation and astronomy - **Construction:** Building pyramids, temples (precise angles crucial)

**Modern Applications:** - **Machine Learning:** Distance defines similarity - **Physics:** Spacetime geometry - **Computer Graphics:** Rendering 3D scenes - **Robotics:** Path planning and localization

#### The Core Problem

How do we quantify “how far apart” two objects are?

Intuitive notions break down: - “Close” vs “far” is subjective - Different paths give different lengths - Need mathematical precision

#### Historical Breakthrough

**Pythagoras (c. 500 BCE)** discovered the relationship in right triangles that enables distance calculation in coordinates:

$$d^2 = (\Delta x)^2 + (\Delta y)^2$$

This formula underlies *all* distance calculations in ML!

### Intuitive Picture

#### Distance

**Physical Analogy:** Measuring tape stretched taut between two points.

**Key Properties:** - Always positive (or zero if points coincide) - Symmetric: distance from A to B equals B to A - Triangle inequality: Direct path is shortest

#### Mental Image:

```

      B
     /|
    / |
   /  | vertical
  /   | distance
 /    |
-----
horiz
dist
A

```

The **straight-line distance** is the hypotenuse.

## Angle

**Physical Analogy:** Amount of “turning” between two directions.

**Examples:** - Clock hands: 12→3 is 90° (quarter turn) - Compass: North→East is 90° - Steering wheel: Amount of rotation

**Mental Image:** Angle = opening between two rays.

## Precise Definitions

### Distance (Euclidean Metric)

**Definition 2.1** (Distance in  $\mathbb{R}^2$ ).

The **distance** between points  $A(x_1, y_1)$  and  $B(x_2, y_2)$  is:

$$d(A, B) = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2}$$

**Generalization to  $\mathbb{R}^n$ :**

$$d(\mathbf{x}, \mathbf{y}) = \sqrt{\sum_{i=1}^n (y_i - x_i)^2} = \|\mathbf{y} - \mathbf{x}\|_2$$

**Metric Properties:** For all points  $A, B, C$ :

1. **Positivity:**  $d(A, B) \geq 0$ , with equality iff  $A = B$
2. **Symmetry:**  $d(A, B) = d(B, A)$
3. **Triangle Inequality:**  $d(A, C) \leq d(A, B) + d(B, C)$

## Angle Measurement

**Definition 2.2** (Angle).

An **angle** is formed by two rays sharing a common endpoint (vertex).

**Units:** - **Degrees:** Full circle = 360° - **Radians:** Full circle =  $2\pi$  rad - **Gradians:** Full circle = 400 grad (rarely used)

**Conversion:**

$$\theta_{\text{rad}} = \theta_{\text{deg}} \times \frac{\pi}{180}$$

**Definition 2.3** (Angle Classification).

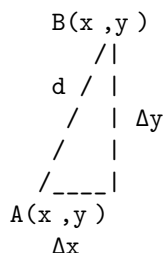
Type	Measure	Visual
<b>Acute</b>	$0^\circ < \theta < 90^\circ$	Sharp
<b>Right</b>	$\theta = 90^\circ$	L-shape
<b>Obtuse</b>	$90^\circ < \theta < 180^\circ$	Wide
<b>Straight</b>	$\theta = 180^\circ$	Line
<b>Reflex</b>	$180^\circ < \theta < 360^\circ$	More than straight



## Why These Definitions

### Why the Square Root Formula?

The distance formula derives from the **Pythagorean theorem**:



By Pythagoras on the right triangle:

$$d^2 = (\Delta x)^2 + (\Delta y)^2$$

Taking the square root gives the distance formula.

**Why squared terms?** - Makes distance always positive - Satisfies triangle inequality - Emerges naturally from inner products in linear algebra

### Why Radians as the “Natural” Unit?

**Radians** defined by:

$$\theta = \frac{s}{r}$$

where  $s$  = arc length,  $r$  = radius.

**Advantages:** 1. **Calculus works cleanly:**  $\frac{d}{dx} \sin x = \cos x$  (only in radians!) 2. **Taylor series simple:**  $\sin x = x - \frac{x^3}{6} + \frac{x^5}{120} - \dots$  3. **Arc length formula:**  $s = r\theta$  (direct, no conversion) 4. **Natural units:**  $\theta = 1$  rad means arc length equals radius

**Degrees are arbitrary:**  $360^\circ$  chosen by Babylonians (base-60 system, divisibility).

## Key Properties

### Properties of Distance

**Theorem 2.1** (Distance Invariance).

Distance is **invariant** under: - **Translation:** Shifting all points by same vector - **Rotation:** Rotating entire figure - **Reflection:** Mirroring across a line

*This is what makes distance a fundamental geometric quantity—it doesn't depend on coordinate system choice.*

**Proof sketch (Translation):**

If we shift  $A \rightarrow A'$  and  $B \rightarrow B'$  by vector  $\mathbf{v}$ :

$$d(A', B') = \|(B + \mathbf{v}) - (A + \mathbf{v})\| = \|B - A\| = d(A, B)$$

### Properties of Angles

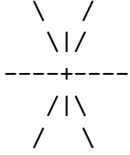
**Theorem 2.2** (Angle Addition).

If ray  $\overrightarrow{OB}$  lies between  $\overrightarrow{OA}$  and  $\overrightarrow{OC}$ :

$$\angle AOC = \angle AOB + \angle BOC$$

**Theorem 2.3** (Vertical Angles).

When two lines intersect, **vertical angles** are congruent.



*Proof:*  $\alpha + \beta = 180^\circ$  and  $\beta + \gamma = 180^\circ$  (linear pairs)  
Therefore  $\alpha = \gamma$  (both equal  $180^\circ - \beta$ ).  $\square$

## Main Theorems

**Theorem 2.4** (Angle Sum in Triangle).

The sum of interior angles in any triangle is  **$180^\circ$** .

**Theorem 2.5** (Exterior Angle Theorem).

An exterior angle of a triangle equals the sum of the two non-adjacent interior angles.

**Theorem 2.6** (Perpendicular Distance).

The shortest distance from point  $P$  to line  $\ell$  is the **perpendicular distance**.

*Proof:* Any other path from  $P$  to  $\ell$  forms the hypotenuse of a right triangle, which is longer than the leg.  $\square$

## Computational Methods

### Computing Distance

```
import math

def euclidean_distance(p1, p2):
    """
    Compute Euclidean distance between two points.

    Args:
        p1, p2: tuples (x, y) or lists [x, y]

    Returns:
        float: Euclidean distance

    Examples:
        >>> euclidean_distance((0, 0), (3, 4))
        5.0
        >>> euclidean_distance((1, 2), (4, 6))
        5.0
    """
    return math.sqrt(sum((a - b)**2 for a, b in zip(p1, p2)))

# Vectorized version for numpy
import numpy as np

def distance_numpy(p1, p2):
    """Numpy implementation for efficiency."""
    return np.linalg.norm(np.array(p2) - np.array(p1))

# Distance matrix for multiple points
def pairwise_distances(points):
    """
```

Compute all pairwise distances.

Args:

points: list of (x, y) tuples

Returns:

2D array of distances

"""

```
n = len(points)
distances = np.zeros((n, n))
for i in range(n):
    for j in range(i+1, n):
        d = euclidean_distance(points[i], points[j])
        distances[i, j] = distances[j, i] = d
return distances
```

## Computing Angles

From three points  $A$ ,  $B$ ,  $C$  (angle at vertex  $B$ ):

```
def angle_from_three_points(A, B, C, degrees=True):
    """
    Compute angle ABC (at vertex B).

    Args:
        A, B, C: tuples (x, y)
        degrees: if True, return degrees; else radians

    Returns:
        float: angle at B

    Examples:
        >>> angle_from_three_points((0,0), (1,0), (1,1))
        90.0
    """
    # Vectors BA and BC
    BA = np.array(A) - np.array(B)
    BC = np.array(C) - np.array(B)

    # Dot product and magnitudes
    dot = np.dot(BA, BC)
    mag_BA = np.linalg.norm(BA)
    mag_BC = np.linalg.norm(BC)

    # Angle from dot product formula
    cos_angle = dot / (mag_BA * mag_BC)
    # Clamp to [-1, 1] to handle numerical errors
    cos_angle = np.clip(cos_angle, -1, 1)
    angle_rad = np.arccos(cos_angle)

    return np.degrees(angle_rad) if degrees else angle_rad
```

## Examples Progression

### Example 1: Simplest

**Problem:** Find distance between  $A(0,0)$  and  $B(3,4)$ .

**Solution:**

$$d = \sqrt{(3-0)^2 + (4-0)^2} = \sqrt{9+16} = \sqrt{25} = 5$$

**Verification:** This is the famous 3-4-5 right triangle!

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### Example 2: Standard

**Problem:** Find distance between  $A(-2,3)$  and  $B(1,7)$  in  $\mathbb{R}^2$ .

**Solution:**

$$d = \sqrt{(1-(-2))^2 + (7-3)^2} = \sqrt{3^2 + 4^2} = \sqrt{9+16} = 5$$

**Observation:** Same distance as Example 1—translation doesn't change distance!

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### Example 3: Higher Dimension

**Problem:** Find distance between  $A(1,2,3)$  and  $B(4,6,8)$  in  $\mathbb{R}^3$ .

**Solution:**

$$d = \sqrt{(4-1)^2 + (6-2)^2 + (8-3)^2} = \sqrt{9+16+25} = \sqrt{50} = 5\sqrt{2}$$

**Pattern:** Pythagorean theorem extends to any dimension!

---

### Example 4: Edge Case

**Problem:** Distance between  $A(2,5)$  and itself.

**Solution:**

$$d = \sqrt{(2-2)^2 + (5-5)^2} = 0$$

**Interpretation:** Only coincident points have distance 0 (metric axiom).

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### Example 5: Non-Example (Manhattan Distance)

**Context:** In a city grid, you can't walk diagonally through buildings.

**Manhattan distance:**  $d_1(A, B) = |x_2 - x_1| + |y_2 - y_1|$

**For  $A(0,0)$ ,  $B(3,4)$ :** - **Euclidean:**  $d_2 = 5$  - **Manhattan:**  $d_1 = 7$

**Note:** This is a different **metric**—satisfies metric axioms but uses different formula.

## Common Pitfalls

### Mistakes to Avoid

#### Pitfall 1: Forgetting Square Root

$$d = \frac{(x_2 - x_1)^2 + (y_2 - y_1)^2}{\sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2}}$$

#### Pitfall 2: Using Degrees in Calculus

$\frac{d}{dx} \sin(x^\circ)$  is undefined!

Always use radians for calculus:  $\frac{d}{dx} \sin x = \cos x$

#### Pitfall 3: Assuming Perpendicular Without Verification

“Lines look perpendicular”

Check: slopes multiply to  $-1$ , or angle =  $90^\circ$  via dot product

#### Pitfall 4: Sign Confusion with Angles

Treating  $270^\circ$  as  $-90^\circ$  inconsistently

Be consistent: counterclockwise positive (standard convention)

#### Pitfall 5: Dimension Mismatch

Applying 2D formula to 3D points

Ensure formula matches dimension:  $d = \sqrt{\sum_{i=1}^n (x_i - y_i)^2}$

## Connections

### Prerequisites

- **Axioms** (Section ): Distance satisfies metric axioms
- **Pythagorean Theorem** (will see in Section ): Foundation of distance formula
- **Number Systems** (Domain 1): Real numbers for measurements

### This Concept Enables

**Within Geometry:** - **Trigonometry** (will cover later): Relates angles to distances - **Circles** (will cover later): Defined by constant distance - **Coordinate Geometry**: Analytic study of shapes

**Other Domains:** - **Domain 4 (Calculus)**: Derivatives as rates of distance change - **Domain 5 (Linear Algebra)**: Inner products generalize angles - **Domain 7 (Real Analysis)**: Metric spaces abstract distance

### ML Applications

**Distance Metrics:** - **k-NN**: Classification by Euclidean distance - **k-Means**: Clustering minimizes within-cluster distances - **Kernel Methods**:  $K(\mathbf{x}, \mathbf{y}) = f(\|\mathbf{x} - \mathbf{y}\|)$

**Angle Metrics:** - **Cosine Similarity**:  $\cos \theta = \frac{\mathbf{x} \cdot \mathbf{y}}{\|\mathbf{x}\| \|\mathbf{y}\|}$  - **Angular Distance**: Used in embeddings (Word2Vec, etc.) - **Gradient Direction**: Angle of steepest ascent

**Optimization:** - **Gradient**:  $\|\nabla f\|$  = magnitude, direction = angle - **Line Search**: Moving distance along gradient direction - **Trust Regions**: Constrain step size (distance)

### Lean Formalization

```
import Mathlib.Analysis.NormedSpace.Basic

-- Euclidean distance
def euclidean_dist (x y : × ) : :=
  Real.sqrt ((x.1 - y.1)^2 + (x.2 - y.2)^2)
```

```

-- Metric properties
theorem dist_nonneg (x y :  $\mathbb{R}^n$ ) :
  0 ≤ euclidean_dist x y := by sorry

theorem dist_sym (x y :  $\mathbb{R}^n$ ) :
  euclidean_dist x y = euclidean_dist y x := by sorry

theorem triangle_ineq (x y z :  $\mathbb{R}^n$ ) :
  euclidean_dist x z ≤ euclidean_dist x y + euclidean_dist y z := by sorry

```

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# The Pythagorean Theorem

## Motivation & Context

### Historical Significance

The Pythagorean theorem is arguably the most important result in elementary mathematics:

**Ancient Knowledge:** - **Babylonians** (c. 1800 BCE): Knew Pythagorean triples - **Pythagoras** (c. 500 BCE): First rigorous proof - **Euclid** (*Elements*, Book I, Prop. 47): Geometric proof - **China** (*Zhou Bi Suan Jing*, c. 300 BCE): Independent discovery

**Over 370 Different Proofs!** - Geometric rearrangements - Algebraic derivations - Calculus-based approaches  
- Even one by U.S. President James Garfield!

### Why It Matters

**Foundation of:** - Distance calculations in coordinates - Trigonometry (sine, cosine, tangent) - Euclidean norm in linear algebra - Spacetime metric in relativity

**ML Applications:** - Every distance calculation uses this theorem - Regularization:  $\|\theta\|_2^2 = \sum \theta_i^2$  - Gradient magnitude:  $\|\nabla f\| = \sqrt{\sum (\partial f / \partial x_i)^2}$  - Neural network initialization: Xavier scales by  $\sqrt{n}$

## Intuitive Picture

### The Setup

Draw a right triangle with: - **Legs:** sides  $a$  and  $b$  (forming the right angle) - **Hypotenuse:** side  $c$  (opposite the right angle, longest side)

### Visual Proof Intuition

Build squares on each side:

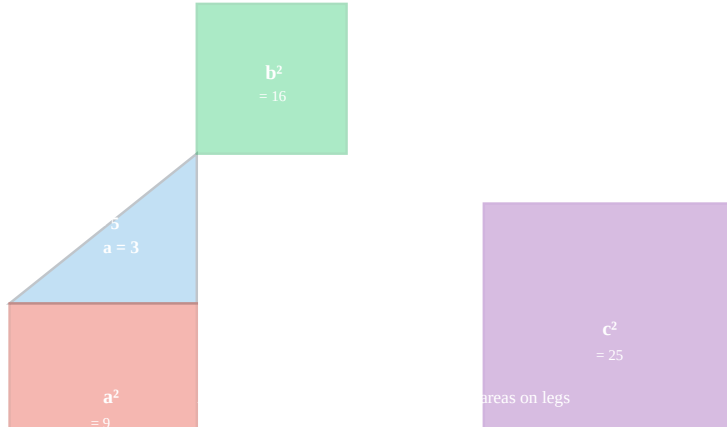


Figure 1: Pythagorean Visual Proof

**Key Insight:** The area of the square on the hypotenuse equals the sum of areas on the two legs:

$$\text{Area}(c^2) = \text{Area}(a^2) + \text{Area}(b^2)$$

This isn't just symbolic—you can literally cut and rearrange the smaller squares to fill the larger one!

## Precise Definition

**Theorem 3.1** (Pythagorean Theorem).

In a right triangle with legs of lengths  $a$  and  $b$ , and hypotenuse of length  $c$ :

$$a^2 + b^2 = c^2$$

**Converse (Theorem 3.2).**

If three sides of a triangle satisfy  $a^2 + b^2 = c^2$ , then the triangle is a right triangle with hypotenuse  $c$ .

## Why These Definitions

### Why Squares of Sides?

**Geometric Reason:** Squares are natural area measurements in Euclidean geometry.

**Algebraic Reason:** Powers of 2 appear naturally in: - Distance formulas:  $d^2 = \Delta x^2 + \Delta y^2$  - Variance:  $\sigma^2 = E[(X - \mu)^2]$  - Least squares: minimize  $\sum (y_i - \hat{y}_i)^2$

**Physical Reason:** Energy scales with square of velocity:  $E = \frac{1}{2}mv^2$

### Why Only Right Triangles?

The perpendicularity ( $90^\circ$  angle) is essential. For other angles:

**Law of Cosines** (generalizes Pythagorean theorem):

$$c^2 = a^2 + b^2 - 2ab \cos C$$

- When  $C = 90^\circ$ :  $\cos 90^\circ = 0$ , so  $c^2 = a^2 + b^2$  (Pythagorean!)
- When  $C < 90^\circ$  (acute):  $\cos C > 0$ , so  $c^2 < a^2 + b^2$
- When  $C > 90^\circ$  (obtuse):  $\cos C < 0$ , so  $c^2 > a^2 + b^2$

## Key Properties

### Pythagorean Triples

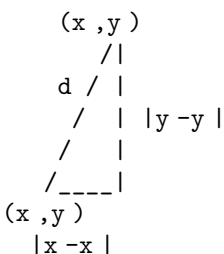
**Definition:** Integer solutions to  $a^2 + b^2 = c^2$ .

**Common Examples:**  $| a | b | c |$  Verification  $| \text{---} | \text{---} | \text{---} | \text{---} |$   $| 3 | 4 | 5 | 9 + 16 = 25 \quad | 5 | 12 | 13 | 25 + 144 = 169 \quad | 8 | 15 | 17 | 64 + 225 = 289 \quad | 7 | 24 | 25 | 49 + 576 = 625 \quad |$

**Property:** If  $(a, b, c)$  is a triple, so is  $(ka, kb, kc)$  for any  $k > 0$ .

### Connection to Distance Formula

The distance between  $(x_1, y_1)$  and  $(x_2, y_2)$  follows from applying Pythagorean theorem:



By Pythagoras:

$$d^2 = (x_2 - x_1)^2 + (y_2 - y_1)^2$$

Therefore:

$$d = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2}$$

This generalizes to  $n$  dimensions!

## Main Theorems (Multiple Proofs)

### Proof 1: Rearrangement (Most Intuitive)

**Setup:** Square of side  $(a + b)$  containing four copies of the triangle.

**Area calculation (two methods):**

**Method 1:** Outer square

$$A_{\text{outer}} = (a + b)^2 = a^2 + 2ab + b^2$$

**Method 2:** Four triangles + inner square

$$A_{\text{triangles} + \text{inner}} = 4 \cdot \frac{1}{2}ab + c^2 = 2ab + c^2$$

**Equating:**

$$a^2 + 2ab + b^2 = 2ab + c^2$$

$$a^2 + b^2 = c^2 \quad \square$$



### Proof 2: Similarity (Geometric)

**Setup:** Drop altitude from right angle to hypotenuse, dividing it into segments  $p$  and  $q$  where  $p + q = c$ .

**Key observation:** Creates three similar triangles: 1. Original: legs  $a, b$ , hypotenuse  $c$  2. Left sub-triangle 3. Right sub-triangle

**From similarity:**

$$\frac{a}{c} = \frac{p}{a} \Rightarrow a^2 = cp$$

$$\frac{b}{c} = \frac{q}{b} \Rightarrow b^2 = cq$$

**Adding:**

$$a^2 + b^2 = cp + cq = c(p + q) = c \cdot c = c^2 \quad \square$$

### Proof 3: Coordinate Geometry

**Setup:** Place right angle at origin, legs along axes.

**Coordinates:**  $O = (0, 0)$ ,  $A = (a, 0)$ ,  $B = (0, b)$

**Distance from  $A$  to  $B$ :**

$$c = \sqrt{(0 - a)^2 + (b - 0)^2} = \sqrt{a^2 + b^2}$$

**Squaring:**

$$c^2 = a^2 + b^2 \quad \square$$

## Computational Methods

### Finding the Third Side

```
import math

def pythagorean_solve(a=None, b=None, c=None):
    """
    Solve for missing side of right triangle.

    Args:
        a, b: legs (one may be None)
        c: hypotenuse (may be None)

    Returns:
        float: the missing side

    Raises:
        ValueError: if not exactly one side is unknown

    Examples:
        >>> pythagorean_solve(b=4, c=5) # find a
        3.0
        >>> pythagorean_solve(a=3, b=4) # find c
        5.0
    """
    unknown_count = sum(x is None for x in [a, b, c])
    if unknown_count != 1:
        raise ValueError("Exactly one side must be unknown")
```

```

if a is None:
    if c <= b:
        raise ValueError("Hypotenuse must be longest side")
    return math.sqrt(c**2 - b**2)
elif b is None:
    if c <= a:
        raise ValueError("Hypotenuse must be longest side")
    return math.sqrt(c**2 - a**2)
else: # c is None
    return math.sqrt(a**2 + b**2)

# Example usage
print(f"3-4-?: {pythagorean_solve(a=3, b=4)}") # 5.0
print(f"5-?-13: {pythagorean_solve(a=5, c=13)}") # 12.0

```

## Generating Pythagorean Triples

**Euclid's Formula:** For integers  $m > n > 0$ :

$$a = m^2 - n^2, \quad b = 2mn, \quad c = m^2 + n^2$$

generates all **primitive** triples (where  $\gcd(a, b, c) = 1$ ).

```

def generate_pythagorean_triples(max_c, primitive_only=True):
    """
    Generate Pythagorean triples up to max hypotenuse.

    Args:
        max_c: maximum hypotenuse value
        primitive_only: if True, only primitive triples

    Returns:
        list of (a, b, c) tuples

    Examples:
        >>> triples = generate_pythagorean_triples(30)
        >>> (3, 4, 5) in triples
        True
    """
    triples = []
    m = 2
    while m**2 + 1 <= max_c:
        for n in range(1, m):
            a = m**2 - n**2
            b = 2 * m * n
            c = m**2 + n**2

            if c > max_c:
                break

            # Ensure a < b for consistency
            if a > b:
                a, b = b, a
        m += 1
    return triples

```

```

        if primitive_only:
            triples.append((a, b, c))
        else:
            # Add multiples
            k = 1
            while k * c <= max_c:
                triples.append((k*a, k*b, k*c))
                k += 1
            m += 1

    return sorted(set(triples), key=lambda t: t[2])

# Generate triples with c = 30
for a, b, c in generate_pythagorean_triples(30):
    print(f"({a}, {b}, {c}): {a}^2 + {b}^2 = {a**2} + {b**2} = {a**2+b**2} = {c}^2 = {c**2}")

```

## Examples Progression

### Example 1: Simplest (3-4-5)

**Given:** Right triangle with legs 3 and 4

**Find:** Hypotenuse

**Solution:**

$$c = \sqrt{3^2 + 4^2} = \sqrt{9 + 16} = \sqrt{25} = 5$$

**Verification:**  $3^2 + 4^2 = 9 + 16 = 25 = 5^2$

---

### Example 2: Standard (Missing Leg)

**Given:** Right triangle with leg 5 and hypotenuse 13

**Find:** Other leg

**Solution:**

$$b = \sqrt{13^2 - 5^2} = \sqrt{169 - 25} = \sqrt{144} = 12$$

**Verification:**  $5^2 + 12^2 = 25 + 144 = 169 = 13^2$

**Note:** This is the 5-12-13 Pythagorean triple!

---

### Example 3: 3D Distance

**Given:** Points  $A(1, 2, 3)$  and  $B(4, 6, 8)$  in space

**Find:** Distance

**Method:** Apply Pythagorean theorem twice:

**Step 1:** Distance in  $xy$ -plane:

$$d_{xy} = \sqrt{(4-1)^2 + (6-2)^2} = \sqrt{9 + 16} = 5$$

**Step 2:** Add  $z$ -component:

$$d = \sqrt{d_{xy}^2 + (8-3)^2} = \sqrt{25 + 25} = \sqrt{50} = 5\sqrt{2}$$

**Direct formula:**

$$d = \sqrt{(4-1)^2 + (6-2)^2 + (8-3)^2} = \sqrt{9 + 16 + 25} = 5\sqrt{2}$$

---

#### Example 4: Edge Case (Degenerate)

**Given:** “Triangle” with sides 0, 4, 4

**Check:**  $0^2 + 4^2 = 0 + 16 = 16 = 4^2$

**Interpretation:** Degenerate case—the two legs are collinear (form a straight line). The “triangle” is actually a line segment of length 4.

---

#### Example 5: Non-Example (Obtuse Triangle)

**Given:** Triangle with sides 3, 4, 6

**Check:**  $3^2 + 4^2 = 9 + 16 = 25$  but  $6^2 = 36$

**Result:**  $25 \neq 36$ , so NOT a right triangle.

**Analysis:**  $25 < 36 \Rightarrow$  **obtuse** triangle (angle opposite longest side  $> 90^\circ$ )

**Law of Cosines:**  $c^2 = a^2 + b^2 - 2ab \cos C$

$$36 = 9 + 16 - 2(3)(4) \cos C$$

$$36 = 25 - 24 \cos C$$

$$\cos C = -\frac{11}{24} < 0$$

Since  $\cos C < 0$ , we have  $C > 90^\circ$  (obtuse).

### Common Pitfalls

#### Mistakes to Avoid

##### Pitfall 1: Forgetting Which Side is Hypotenuse

$$5^2 + 13^2 = c^2 \text{ (treating 13 as a leg)}$$

Hypotenuse is **always** opposite the right angle and is the **longest** side

##### Pitfall 2: Using for Non-Right Triangles

Applying  $a^2 + b^2 = c^2$  to any triangle

For non-right triangles, use Law of Cosines:  $c^2 = a^2 + b^2 - 2ab \cos C$

##### Pitfall 3: Arithmetic Errors

$$(c-a)^2 = c^2 - a^2 \text{ (WRONG!)}$$

$$c^2 - a^2 \neq (c-a)^2; \text{ must use } b = \sqrt{c^2 - a^2}$$

##### Pitfall 4: Negative “Solutions”

Accepting  $c = -5$  as a solution

Side lengths must be **positive**:  $c = 5$

##### Pitfall 5: Confusing $a^2 + b^2 = c^2$ with $a + b = c$

$$3 + 4 = 7 \neq 5, \text{ so theorem wrong?}$$

It's  $3^2 + 4^2 = 9 + 16 = 25 = 5^2$   
**Pitfall 6: Rounding Too Early**  
 $\sqrt{50} \approx 7$ , so use 7  
 Keep exact:  $\sqrt{50} = 5\sqrt{2} \approx 7.071$

## Connections

### Prerequisites

- **Axioms** (Section ): Geometric foundations
- **Distance** (Section ): Measuring lengths
- **Congruence** (coming): Proving triangles equal

### This Concept Enables

**Immediate Applications:** - **Distance Formula:** Direct application - **Trigonometry:** Foundation for trig functions - **Circles:** Computing chord lengths, tangent properties

**Advanced Topics:** - **Euclidean Norm** (Linear Algebra):  $\|\mathbf{x}\| = \sqrt{x_1^2 + \dots + x_n^2}$  - **Arc Length** (Calculus):  $s = \int \sqrt{1 + (f')^2} dx$  - **3D Geometry:** Spatial distances and vectors

## ML Applications

### Distance Metrics:

```
# Euclidean distance (L norm)
def l2_norm(x):
    return np.sqrt(np.sum(x**2)) # Direct application!

# Used in:
# - k-NN classification
# - k-Means clustering
# - Gaussian RBF kernel
```

### Gradient Magnitude:

$$\|\nabla f\| = \sqrt{\left(\frac{\partial f}{\partial x}\right)^2 + \left(\frac{\partial f}{\partial y}\right)^2 + \dots}$$

### Regularization (L penalty):

$$\text{Loss} = \text{MSE} + \lambda \|\theta\|_2^2 = \text{MSE} + \lambda \sum_{i=1}^n \theta_i^2$$

### Neural Network Initialization:

Xavier/He initialization scales weights by  $\frac{1}{\sqrt{n}}$  where  $n$  = number of inputs. This comes from variance calculations using Pythagorean-style sums!

## Historical Note

**Proof #371:** Yes, there really are over 370 known proofs! See *The Pythagorean Proposition* by Elisha Loomis (1927) for a collection of 371 proofs.

**Most unusual:** President James A. Garfield's proof (1876) using trapezoid area.

## Lean Formalization

```
import Mathlib.Geometry.Euclidean.Basic

-- Pythagorean theorem statement
theorem pythagoras {a b c : ℝ} (h : RightTriangle a b c) :
  c^2 = a^2 + b^2 := by
  sorry -- Proof omitted

-- Converse
theorem pythagoras_converse {a b c : ℝ}
  (h : c^2 = a^2 + b^2) :
  RightTriangle a b c := by
  sorry

-- Application: distance formula
theorem distance_formula (p q : ℝ × ℝ) :
  dist p q = Real.sqrt ((p.1 - q.1)^2 + (p.2 - q.2)^2) := by
  -- Follows from Pythagorean theorem
  sorry
```

## Interactive Exploration

### 💡 Try It Yourself!

Use the interactive visualization below to explore the Pythagorean theorem dynamically. Adjust the leg lengths and watch how the squares' areas relate:

**Observations to make:** - The equation  $a^2 + b^2 = c^2$  holds for all leg combinations - As you increase  $a$  or  $b$ , the hypotenuse  $c$  grows predictably - The visual proof becomes clear: areas on the legs sum to area on hypotenuse

## Practice Problems

### 💡 Expand for Problems with Solutions

#### Problem 1: Distance Calculation

**Given:** Points  $A(-3, 2)$  and  $B(5, 8)$  in  $\mathbb{R}^2$

**Find:** Distance between  $A$  and  $B$

Solution (click to reveal)

$$d = \sqrt{(5 - (-3))^2 + (8 - 2)^2} = \sqrt{8^2 + 6^2} = \sqrt{64 + 36} = \sqrt{100} = 10$$

**Answer:** 10 units

#### Problem 2: Pythagorean Application

**Given:** A 20-foot ladder leans against a wall. The base is 12 feet from the wall.

**Find:** Height the ladder reaches on the wall

Solution (click to reveal)

Let  $h$  = height on wall. We have a right triangle with: - Hypotenuse:  $c = 20$  ft (ladder) - Base:  $a = 12$  ft - Height:  $b = h$  ft (unknown)

By Pythagorean theorem:

$$12^2 + h^2 = 20^2$$

$$144 + h^2 = 400$$

$$h^2 = 256$$

$$h = 16 \text{ ft}$$

**Answer:** 16 feet high

**Verification:**  $12^2 + 16^2 = 144 + 256 = 400 = 20^2$

**Note:** This is a multiple of the 3-4-5 triple:  $(12, 16, 20) = 4 \times (3, 4, 5)$

---

### Problem 3: Congruence Proof

**Given:**  $\triangle ABC$  and  $\triangle DEF$  with: -  $AB = 8$ ,  $BC = 10$ ,  $CA = 12$

-  $DE = 8$ ,  $EF = 10$ ,  $FD = 12$

**Prove:** The triangles are congruent

Solution (click to reveal)

**Proof:**

1.  $AB = DE = 8$  (given)

2.  $BC = EF = 10$  (given)

3.  $CA = FD = 12$  (given)

4. Therefore  $\triangle ABC \cong \triangle DEF$  by **SSS** (Side-Side-Side)  $\square$

**Conclusion:** The triangles are congruent. All corresponding parts are equal.

---

### Problem 4: Non-Right Triangle

**Given:** Triangle with sides 7, 8, 12

**Question:** Is this a right triangle? If not, is it acute or obtuse?

Solution (click to reveal)

**Check:** Does  $7^2 + 8^2 = 12^2$ ?

$$49 + 64 = 113 \neq 144$$

So it's **not** a right triangle.

**Determine acute vs obtuse:**

$$7^2 + 8^2 = 113 < 144 = 12^2$$

Since  $a^2 + b^2 < c^2$ , the triangle is **obtuse** (angle opposite longest side  $> 90^\circ$ ).

**Verification with Law of Cosines:**

$$\cos C = \frac{a^2 + b^2 - c^2}{2ab} = \frac{49 + 64 - 144}{2(7)(8)} = \frac{-31}{112} < 0$$

Since  $\cos C < 0$ , we have  $90^\circ < C < 180^\circ$  (obtuse).

**Answer:** Obtuse triangle

---

**Problem 5: 3D Distance**

**Given:** Points  $P(2, -1, 3)$  and  $Q(5, 3, -1)$  in  $\mathbb{R}^3$

**Find:** Distance  $PQ$

Solution (click to reveal)

Apply 3D distance formula:

$$d = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$$

$$\begin{aligned} d &= \sqrt{(5 - 2)^2 + (3 - (-1))^2 + ((-1) - 3)^2} \\ &= \sqrt{3^2 + 4^2 + (-4)^2} \\ &= \sqrt{9 + 16 + 16} \\ &= \sqrt{41} \end{aligned}$$

**Answer:**  $\sqrt{41} \approx 6.40$  units

**Note:** This is NOT a Pythagorean triple (41 is not a perfect square).